

Differential Equations Review

Fundamentals of Engineering Examination

Tony Thomas
Department of Mathematics
University of Wisconsin-Platteville

SECTION I

Equations of Order One

1. *Separation of Variables:* Consider the equation $M(x, y)dx + N(x, y)dy = 0$. If this equation can be put in the form $f(x)dx = g(y)dy$, we say that the variables can be separated. Then, the solution may be obtained by integrating both sides.

1.1. Solve the equation $\frac{dy}{dx} = \frac{y^2}{1-x}$. ANSWER: $y = \frac{1}{\ln|C(1-x)|}$, where C is a constant of integration.

1.2. Solve the equation $\frac{dV}{dP} = -\frac{V}{P}$. ANSWER: $V = C/P$, where C is a constant of integration.

1.3. Solve the equation $\frac{dx}{dt} = \frac{\csc^2 x}{1+t^2}$. ANSWER: $x - \sin x \cos x = 2 \tan^{-1} t + C$, where C is a constant of integration.

2. *Homogeneous Coefficients:* Consider the equation $M(x, y)dx + N(x, y)dy = 0$. If this equation can be put in the form $y' = f(y/x)$, then making the substitution $v = y/x$ will yield a separable equation.

REMARK: In certain cases it may be easier to set $v = x/y$ instead.

2.1. Solve the equation $(x^2 - xy + y^2)dx - xy dy = 0$. ANSWER: $(y - x) \exp(y/x) = C$, where C is a constant of integration.

3. *Exact Equations:* If a function $F(x, y)$ exists such that $dF = M dx + N dy = 0$, we call the equation $M dx + N dy = 0$ exact. Recall that $dF = (\partial F/\partial x)dx + (\partial F/\partial y)dy$. Therefore, if the equation $M dx + N dy = 0$ is exact, then $M = \partial F/\partial x$ and $N = \partial F/\partial y$.

THEOREM: If $M, N, \partial M/\partial y$, and $\partial N/\partial x$ are continuous on a simply connected open set, then $M dx + N dy = 0$ is exact if and only if $\partial M/\partial y = \partial N/\partial x$.

The solution to an exact equation is found by “partial integration” and is given by $F(x, y) = C$, where C is a constant of integration.

3.1. Find the solution of the equation $3x(xy-2)dx + (x^3 + 2y)dy = 0$, which passes through the point $(1,0)$. ANSWER: $x^3y - 3x^2 + y^2 + 3 = 0$.

4. *Linear Equations:* A first-order differential equation of the form $\frac{dy}{dx} + P(x)y = Q(x)$ is called linear. This equation may be solved by multiplying both sides by the integrating factor $\mu(x) = \exp\left(\int P(x)dx\right)$. This causes the left side of the equation to become $\frac{d}{dx}(\mu \cdot y)$, i.e. exact.

WARNING: The coefficient of y' must be 1.

4.1. Solve the equation $2(y-4x^2)dx + xdy = 0$. ANSWER: $y = 2x^2 + Cx^{-2}$, where C is a constant of integration.

Equations of Order Two

5. *Equations of the form $d^2y/dx^2 = f(x, dy/dx)$:* Make the substitution $dy/dx = v$ (and therefore $d^2y/dx^2 = v'$) in order to reduce the equation to order one.

5.1. Solve the equation $y'' = 5(y')^2$. ANSWER: $y = -\frac{1}{5} \ln|C_1 + 5x| + C_2$, where C_1 and C_2 are constants of integration.

5.2. Solve the equation $xy'' = y' + x^5$ subject to the conditions that when $x=1$ we have $y=1/2, y'=1$. ANSWER: $24y = x^6 + 9x^2 + 2$.

6. *Equations of the form $d^2y/dx^2 = f(y, dy/dx)$:* Make the substitution $dy/dx = v$ (and therefore $d^2y/dx^2 = v \cdot dv/dy$) in order to reduce the equation to order one.

REMARK: The fact that $d^2y/dx^2 = v \cdot dv/dy$ comes from the chain rule, specifically $d^2y/dx^2 = dv/dx = dv/dy \cdot dy/dx = dv/dy \cdot v$.

6.1. Solve the equation $yy'' + (y')^2 = 0$. ANSWER: $y^2 = C_1x + C_2$, where C_1 and C_2 are constants of integration.

7. *Linear equations with constant coefficients, $ay'' + by' + cy = 0$:* Finding the roots r_1 and r_2 of the auxiliary equation $ar^2 + br + c = 0$ leads to the solution as follows.

Case 1: $r_1 \neq r_2$ both real $\Rightarrow y = C_1 e^{r_1 x} + C_2 e^{r_2 x}$, where C_1 and C_2 are constants of integration.

Case 2: $r_1 = r_2 \Rightarrow y = C_1 e^{r_1 x} + C_2 x e^{r_1 x}$, where C_1 and C_2 are constants of integration.

Case 3: $r_1 = a + bi, r_2 = a - bi \Rightarrow y = C_1 e^{ax} \cos bx + C_2 e^{ax} \sin bx$, where C_1 and C_2 are constants of integration.

REMARK: This method may be extended to linear differential equations with constant coefficients whose order is higher than two.

7.1. Solve the equation $y'' - 6y' + 10y = 0$. ANSWER: $y = C_1 e^{3x} \cos x + C_2 e^{3x} \sin x$, where C_1 and C_2 are constants of integration.

7.2. Solve the equation $y'' + 4y' + 4y = 0$ subject to the initial conditions $y(0) = 1, y'(0) = -1$. ANSWER: $y = (1+x)e^{-2x}$.

8. *Method of Undetermined Coefficients:* The solution of the linear differential equation with constant coefficients $ay'' + by' + cy = f(x)$ is $y = y_h + y_p$ where y_h is the general solution to the associated homogeneous equation $ay'' + by' + cy = 0$ and y_p is any particular solution of $ay'' + by' + cy = f(x)$. The method of undetermined coefficients is based on making a judicious guess as to the form of y_p .

8.1. Solve the equation $y'' + y' - 2y = 2x - 40 \cos 2x$.

ANSWER: $y = C_1 e^x + C_2 e^{-2x} - \frac{1}{2}x + 6 \cos 2x - 2 \sin 2x$, where C_1 and C_2 are constants of integration.

8.2. Solve the equation $y'' + 4y = 8e^{2x} + 12x$.

ANSWER: $y = C_1 \cos 2x + C_2 \sin 2x + 3x + e^{2x}$, where C_1 , and C_2 are constants of integration.

9. *Reduction of Order:* Consider the linear differential equation of order two $y'' + P(x)y' + Q(x)y = 0$. If we know one solution $y = y_1$, then a second linearly independent solution $y = y_2$ is given by

$$y_2 = y_1 \cdot \int \frac{\exp\left(-\int P(x) dx\right)}{[y_1(x)]^2} dx.$$

WARNING: The coefficient of y'' must be 1.

9.1. Verify that $y = x$ is one solution of the Legendre differential equation $(1-x^2)y'' - 2xy' + 2y = 0$. Find a second solution.

ANSWER: $y = -2 + x \ln \left| \frac{1+x}{1-x} \right|$.

10. *Variation of Parameters:* Consider the linear differential equation of order two $y'' + P(x)y' + Q(x)y = R(x)$. If we know two linearly independent solutions y_1 and y_2 of the corresponding homogeneous equation $y'' + P(x)y' + Q(x)y = 0$, then a particular solution of $y'' + P(x)y' + Q(x)y = R(x)$ is given by $y_p = v_1(x)y_1(x) + v_2(x)y_2(x)$ where

$$v_1(x) = \int \frac{-R(x)y_2(x)}{W(x)} dx \quad \text{and} \quad v_2(x) = \int \frac{R(x)y_1(x)}{W(x)} dx$$

Note: $W(x) = y_1(x)y_2'(x) - y_1'(x)y_2(x)$ is the Wronskian of y_1 and y_2 .

10.1. Solve the equation $y'' - 3y' + 2y = 1/(1 + e^{-x})$.

ANSWER: $y = C_1 e^x + C_2 e^{2x} + (e^x + e^{2x}) \ln(1 + e^{-x})$, where C_1 and C_2 are constants of integration.

11. *Laplace Transforms:* The Laplace transform of f is defined by

$$\mathcal{L}\{f\}(s) = F(s) = \int_0^{\infty} e^{-st} f(t) dt.$$

The Laplace transform obeys the linearity property

$$\mathcal{L}\{af(t) + bg(t)\}(s) = aF(s) + bG(s)$$

where a and b are constants.

Some basic formulas for the Laplace transform are:

$$\begin{aligned} \mathcal{L}\{1\}(s) &= \frac{1}{s} & \mathcal{L}\{\cos kt\}(s) &= \frac{s}{s^2 + k^2} \\ \mathcal{L}\{t^n\}(s) &= \frac{n!}{s^{n+1}}, \quad n = 1, 2, 3, \dots & \mathcal{L}\{e^{at} \sin kt\}(s) &= \frac{k}{(s-a)^2 + k^2} \\ \mathcal{L}\{e^{at}\}(s) &= \frac{1}{s-a} & \mathcal{L}\{e^{at} \cos kt\}(s) &= \frac{(s-a)}{(s-a)^2 + k^2} \\ \mathcal{L}\{t^n e^{at}\}(s) &= \frac{n!}{(s-a)^{n+1}}, \quad n = 1, 2, 3, \dots & \mathcal{L}\{f'\}(s) &= s \mathcal{L}\{f\}(s) - f(0) \\ \mathcal{L}\{\sin kt\}(s) &= \frac{k}{s^2 + k^2} & \mathcal{L}\{f''\}(s) &= s^2 \mathcal{L}\{f\}(s) - sf(0) - f'(0) \end{aligned}$$

Solving an initial value problem using the method of Laplace transforms.

- i) Take the Laplace transform of both sides of the equation.
- ii) Obtain and solve an (algebraic) equation for the Laplace transform of the solution.
- iii) Determine the solution of the initial value problem by inverting the Laplace transform in part ii).

11.1. Solve the initial value problem $y'(t) + 3y(t) = 13 \sin 2t$; $y(0) = 6$.

ANSWER: $y(t) = 8e^{-3t} - 2 \cos 2t + 3 \sin 2t$.

REMARK: This problem could have been solved by the method of item 7.

11.2. Solve the initial value problem $y''(t) + 2y'(t) + y(t) = 3te^{-t}$; $y(0) = 4$, $y'(0) = 2$.

ANSWER: $y(t) = (4 + 6t + \frac{1}{2}t^3)e^{-t}$.

REMARK: This problem could have been solved by the method of item 8 or item 10.

12. *Cauchy-Euler Equation*: The linear differential equation of order two

$$ax^2 \frac{d^2 y}{dx^2} + bx \frac{dy}{dx} + cy = 0,$$

where a , b , and c are constants, may be solved by substituting $y = x^r$ into the equation and solving for r .

12.1. Solve the equation $2x^2 y'' + xy' - y = 0$. ANSWER: $y = C_1 x + C_2 x^{-1/2}$, where C_1 and C_2 are constants of integration.

SECTION II

Problems for further review.

1. $xy^3 dx + e^{x^2} dy = 0$. ANSWER: $e^{-x^2} + y^{-2} = C$.
2. $x \cos^2 y dx + \tan y dy = 0$. ANSWER: $x^2 + \tan^2 y = C^2$.
3. $x^2 y' = 4x^2 + 7xy + 2y^2$. ANSWER: $x^2(y + 2x) = C(y + x)$.
4. $y(9x - 2y)dx - x(6x - y)dy = 0$; when $x = 1$, $y = 1$. ANSWER: $3x^3 - x^2 y - 2y^2 = 0$.
5. $(1 + y^2 + xy^2)dx + (x^2 y + y + 2xy)dy = 0$. ANSWER: $2x + y^2(1 + x)^2 = C$.
6. $(r + \sin \theta - \cos \theta)dr + r(\sin \theta + \cos \theta)d\theta = 0$. ANSWER: $r^2 + 2r(\sin \theta - \cos \theta) = C$.
7. $y' = x - 2xy$. Solve by two different methods. ANSWER: $2y = 1 + Ce^{-x^2}$.
8. $(2x + 3)y' = y + (2x + 3)^{1/2}$; when $x = -1$, $y = 0$. ANSWER: $2y = (2x + 3)^{1/2} \ln(2x + 3)$.
9. $y^2 y'' + (y')^3 = 0$. ANSWER: $x = C_1 y - \ln|C_2 y|$.
10. $y'' \cos x = y'$. ANSWER: $y = C_2 + C_1 \ln(1 - \sin x)$.
11. $y'' = 2y(y')^3$. ANSWER: $y^3 = 3(C_2 - x - C_1 y)$.
12. $y'' = -e^{-2y}$; when $x = 3$, $y = 0$, $y' = -1$. ANSWER: $y = \ln(4 - x)$.
13. $y'' + 6y' + 9 = 0$. ANSWER: $y = (C_1 + C_2 x)e^{-3x}$.
14. $2y^{(4)} - 3y''' - 2y'' = 0$. ANSWER: $y = C_1 + C_2 x + C_3 e^{2x} + C_4 e^{-x/2}$.

15. $y'' - 4y' + 7y = 0$. ANSWER: $y = C_1 e^{2x} \cos \sqrt{3}x + C_2 e^{2x} \sin \sqrt{3}x$.
16. $y^{(4)} + 2y''' + 10y'' = 0$. ANSWER: $y = C_1 + C_2 x + C_3 e^{-x} \cos 3x + C_4 e^{-x} \sin 3x$.
17. $y^{(4)} + 18y'' + 81y = 0$. ANSWER: $y = (C_1 + C_2 x) \cos 3x + (C_3 + C_4 x) \sin 3x$.
18. $y'' + y' = \sin x$. ANSWER: $y = C_1 + C_2 e^{-x} - \frac{1}{2} \sin x - \frac{1}{2} \cos x$.
19. $y'' - 3y' - 4y = 5e^{4x}$. ANSWER: $y = (C_1 + x)e^{4x} + C_2 e^{-x}$.
20. $y'' + 3y' = -18x$; when $x = 0, y = 0, y' = 5$. ANSWER: $y = 1 + 2x - 3x^2 - e^{-3x}$.
21. $y'' + 2y' + y = (e^x - 1)^{-2}$. ANSWER: $y = e^{-x} (C_1 + C_2 x - \ln |1 - e^{-x}|)$.
22. Verify that $y = e^x$ is a solution of $(x-1)y'' - xy' + y = 0$. Find the general solution of $(x-1)y'' - xy' + y = 1$. ANSWER: $y = C_1 x + C_2 e^x + 1$.
23. $y'' + y = \sec^3 x$. Solve by two different methods.
ANSWER: $y = C_1 \cos x + C_2 \sin x + \frac{1}{2} \sec x$.
24. $y''(t) - 3y'(t) + 2y(t) = e^{3t}$; $y(0) = 0, y'(0) = 0$. Solve by two different methods.
ANSWER: $y = \frac{1}{2} e^t - e^{2t} + \frac{1}{2} e^{3t}$.
25. $y''(t) - 4y'(t) + 4y(t) = 4 \cos 2t$; $y(0) = 2, y'(0) = 5$. Solve by two different methods.
ANSWER: $y = 2e^{2t} (1+t) - \frac{1}{2} \sin 2t$.
26. $x^2 y'' + 2xy' - 12y = 0$. ANSWER: $y = C_1 x^3 + C_2 x^{-4}$.
27. $x^2 y'' - 3xy' + 4y = 0$. ANSWER: $y = x^2 (C_1 + C_2 \ln x)$.
28. *Newton's Law of Cooling*: Let $T(t)$ represent the temperature of an object at time t and suppose that this object is placed in an environment where the ambient temperature at time t is given by $M(t)$. Experimental evidence shows that a good model of this situation is given by the equation $dT/dt = k(M(t) - T(t))$ where k is a constant of proportionality.
- 28.1. Suppose that a thermometer, which has been at the reading 70°F inside a house, is placed outside where the air temperature is 10°F . Three minutes later it is found that the thermometer reading is 25°F . Show that $T(t) = 10 + 60 \exp(-\frac{1}{3}t \ln 4)$.
29. *Mechanical Vibrations*: Suppose a weight with mass m is suspended from a spring with spring constant k . Let $x(t)$ represent the distance of the weight from equilibrium at time t where downward is taken as the positive direction. This situation can be modeled

by the differential equation $mx''(t) + bx'(t) + kx(t) = f(t)$ where b is a damping constant and $f(t)$ is a forcing function.

REMARK: Recall that *Hooke's Law* states the following. A spring stretched from its rest position exerts a restoring force \mathbf{F} whose magnitude is $F = ks$, where s is the amount of elongation of the spring and $k > 0$ is the spring constant.

29.1. *Undamped Vibrations* ($b = 0$): The differential equation becomes $x''(t) + \beta^2 x(t) = f(t)$ where $\beta^2 = k/m$. Notice that a factor of $1/m$ has been absorbed into the forcing function.

29.1.1. Suppose that a spring is such that it would be stretched 6 inches by a 12-lb. weight. Let the weight be attached to the spring and pulled down 4 inches below the equilibrium point. If the weight is started with an upward velocity of 2 ft/sec, describe the motion. Assume that no damping or forcing function is present. Show that $x(t) = -\frac{1}{4} \sin 8t + \frac{1}{3} \cos 8t$.

29.1.2. Suppose that the forcing function in 29.1 is given by $f(t) = A \sin \omega t$ where $\omega \neq \beta$. Assuming the initial conditions are $x(0) = x_0$ and $x'(0) = v_0$, show that

$$x(t) = \frac{v_0}{\beta} \sin \beta t + x_0 \cos \beta t - \frac{A\omega}{\beta(\beta^2 - \omega^2)} \sin \beta t + \frac{A}{\beta^2 - \omega^2} \cos \beta t.$$

REMARK: The case where $A = 0$ is exactly the case where no forcing function is present. Compare the solution of 29.1.2, with $A = 0$, to the solution of 29.1.1.

29.1.3. Suppose that the forcing function in 29.1 is given by $f(t) = A \sin \omega t$ where $\omega = \beta$ (this is the case of resonance). Assuming the initial conditions are $x(0) = x_0$ and $x'(0) = v_0$, show that

$$x(t) = \frac{v_0}{\beta} \sin \beta t + x_0 \cos \beta t + \frac{A}{2\beta^2} (\sin \beta t - \beta t \cos \beta t).$$

29.2. *Damped Vibrations*: The differential equation becomes $x''(t) + 2\gamma x'(t) + \beta^2 x(t) = f(t)$ where $2\gamma = b/m$. Assume the initial conditions are $x(0) = x_0$, $x'(0) = v_0$ and there is no forcing function.

29.2.1. *Underdamped (or Oscillatory) Motion*: This is the case where $\beta > \gamma$. Show that $x(t) = e^{-\gamma t} (c_1 \cos \delta t + c_2 \sin \delta t)$ where $\delta^2 = \beta^2 - \gamma^2$, $\delta > 0$.

29.2.2. *Critically Damped Motion*: This is the case where $\beta = \gamma$. Show that $x(t) = e^{-\gamma t} (c_1 + c_2 t)$.

29.2.3. *Overdamped Motion:* This is the case where $\beta < \gamma$. Show that

$$x(t) = c_1 e^{(-\gamma+\sigma)t} + c_2 e^{(-\gamma-\sigma)t} \text{ where } \sigma^2 = \gamma^2 - \beta^2, \sigma > 0.$$

REMARK: It is very instructive to choose specific values for m , b , k , x_0 , v_0 , and to compare the graphs of x versus t in the cases where motion is underdamped, critically damped, and overdamped.